

Date am / pm

Course Hand: Port / Starboard

Triangle: 45 / 60 deg

Wind Bearing

Ref Point

Bottom Mark is Reference

	Top Mark
	GPS
Bearing = Wind Bearing <input type="text"/>	
Back Bearing (to Bottom Mark)	<input type="text"/>
Distance from Bottom Mark (beat length)	<input type="text"/>

Wing/Gybe Mark

	GPS
XXX = Internal Angle of Bottom to Wing <input type="text"/>	
Bearing = Wind Bearing +/- XXX # <input type="text"/>	
Back Bearing (to Bottom Mark)	<input type="text"/>
Distance from Bottom Mark (reach length)	<input type="text"/>
# - for Port Course	
+ for Starbord Course	
reach = beat for 60 degrees	
reach = 0.7 beat for 45 degrees	

Top Mark is Reference

	Bottom Mark
	GPS
Bearing (to Top Mark) = Wind Bearing <input type="text"/>	
Distance from Top Mark (beat length)	<input type="text"/>

Wing/Gybe Mark

	GPS
XXX = Internal Angle of Top to Wing <input type="text"/>	
Bearing = Wind Bearing +/- XXX # <input type="text"/>	
Distance from Bottom Mark (reach length)	<input type="text"/>
# + for Port Course	
- for Starbord Course	
reach = beat for 60 degrees	
reach = 0.7 beat for 45 degrees	